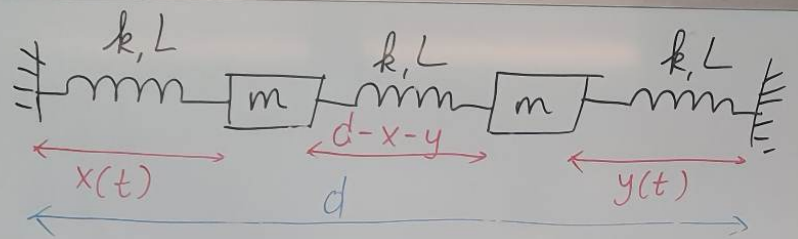


L

9.6.



a/ (1): $m \frac{d^2x}{dt^2} = -k(x-L) + k(d-x-y-L)$

(2): $m \frac{d^2y}{dt^2} = -k(y-L) + k(d-x-y-L)$

Equilibrium: $\begin{cases} -k(x-L) + k(d-x-y-L) = 0 \\ -k(y-L) + k(d-x-y-L) = 0 \end{cases}$

$$\begin{cases} -x + L + d - x - y - L = 0 \\ -y + L + d - x - y - L = 0 \end{cases}$$

$$\begin{cases} -2x - y + d = 0 \quad (*) \\ -x - 2y + d = 0 \quad (**) \end{cases}$$

$(*) \cdot 2 - (**): -3x + d = 0 \Rightarrow x = \frac{d}{3}$

plug in (**): $-\frac{d}{3} - 2y + d = 0$

$C_1 + C_2 e^{5t} \Rightarrow y = \frac{d}{3}$

$\lambda^2 - 5\lambda = 0 \quad \lambda = 0, \lambda = 5$

$$\begin{cases} \frac{d^2y}{dt^2} = 5y \\ y'' = 5y \\ y'' - 5y = 0 \end{cases}$$

$$y - l = 0$$

$$y - l = 0$$

$$= 0 \quad (*)$$

$$= 0 \quad (**)$$

$$-3x + d = 0 \rightarrow x = \frac{d}{3}$$

$$-2y + d = 0$$

$$\frac{d^2 y}{dt^2} = 5y$$

$$y'' = 5y$$

$$y'' - 5y = 0$$

$$n=5$$

$$b \quad \boxed{d - x - y} = d - (x+y) = z(t) \Rightarrow \frac{d^2 z}{dt^2} = -\frac{d^2}{dt^2} (x+y)$$

(1) + (2):

$$d - z = (x+y)$$

$$m \frac{d^2}{dt^2} (x+y) = -k(x+y-2L) + 2k(d-x-y-L)$$

$$m \left(-\frac{d^2 z}{dt^2} \right) = -k(d-z-2L) + 2k(z-L)$$

$$\begin{aligned} -m \frac{d^2 z}{dt^2} &= -kd + kz + 2Lk + 2kz - 2kL \\ &= -kd + 3kz \end{aligned}$$

$$-m \frac{d^2 z}{dt^2} = k(3z-d)$$

$$-m \frac{d^2 z}{dt^2} = 3k(z - \frac{d}{3}) \Rightarrow z \text{ is oscillation}$$

$$T = \frac{2\pi}{\omega} = 2\pi \frac{1}{\omega} = 2\pi \sqrt{\frac{3k}{m}} \quad \omega = \sqrt{\frac{m}{3k}}$$

$$c) (1)-(2): m \frac{d^2}{dt^2} (x-y) = -k(x-y) \quad \boxed{B=x-y}$$

$$m \frac{d^2 B}{dt^2} = -kB \quad T = 2\pi \frac{1}{\omega} = 2\pi \sqrt{\frac{m}{k}}$$

Basillate

d/ If $d - x - y = C \stackrel{?}{=} L$

$$m \frac{d^2x}{dt^2} = -k(x-L)$$

$$m \frac{d^2y}{dt^2} = -k(y-L)$$



e/ (1): $m \frac{d^2x}{dt^2} = -k(x-L)$

$$m \frac{d^2x}{dt^2} = -k(3x - d)$$

$$= -3k \left(x - \frac{d}{3} \right)$$

$$T = 2\pi \sqrt{\frac{3k}{m}}$$

9.6..



a/ (1): $m \frac{d^2x}{dt^2} =$

(2): $m \frac{d^2y}{dt^2} =$

Equilibrium:

$$10.4 \quad F_f = \begin{cases} \gamma & \text{for } \frac{dx}{dt} < 0 \\ -\gamma & \frac{dx}{dt} > 0 \end{cases}$$

a / sign of γ : $\gamma > 0$, so that $F_f > 0$ when $\frac{dx}{dt} < 0$.

b / dimension of γ : dimension of force.

$$c / \quad m \frac{d^2x}{dt^2} = -kx - c \frac{dx}{dt}$$

$$F_f = -c \frac{dx}{dt}$$

equilibrium: $\frac{d^2x}{dt^2} = 0$

$$m \frac{d^2x}{dt^2} = -kx + F_f$$

$$0 = -kx + F_f$$

$$e / (1): m \frac{d^2x}{dt^2} = -k(x-L)$$

$$m \frac{d^2x}{dt^2} = -k(3x - d)$$

$$= -3k(x - \frac{d}{3})$$

$$T = 2\pi \sqrt{\frac{m}{3k}}$$

$$x = \frac{F_f}{k} = \begin{cases} \frac{\gamma}{k} & : \frac{dx}{dt} < 0 \\ -\frac{\gamma}{k} & : \frac{dx}{dt} > 0 \end{cases}$$

$$|F_f| \leq \gamma$$

$$\text{then: } |x| = \frac{|F_f|}{k} \leq \frac{\gamma}{k}$$

b

(1

m

m

-m